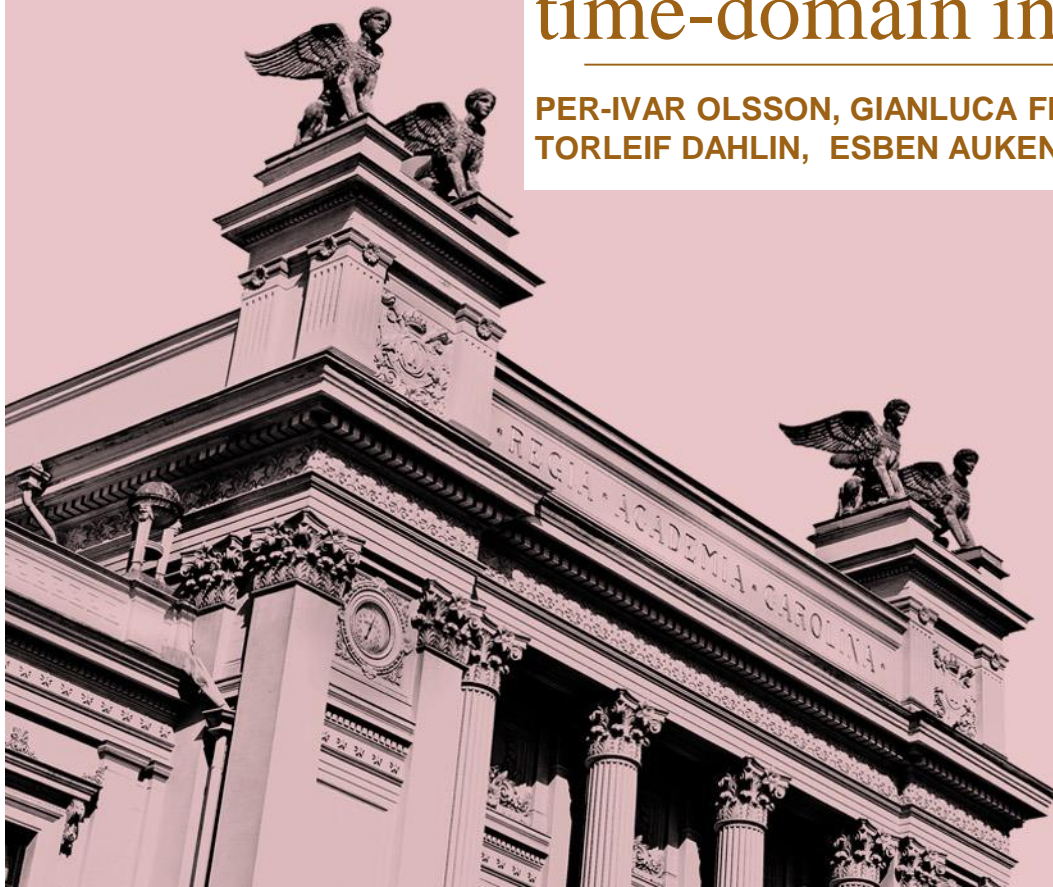




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# Doubling the spectrum of time-domain induced polarization

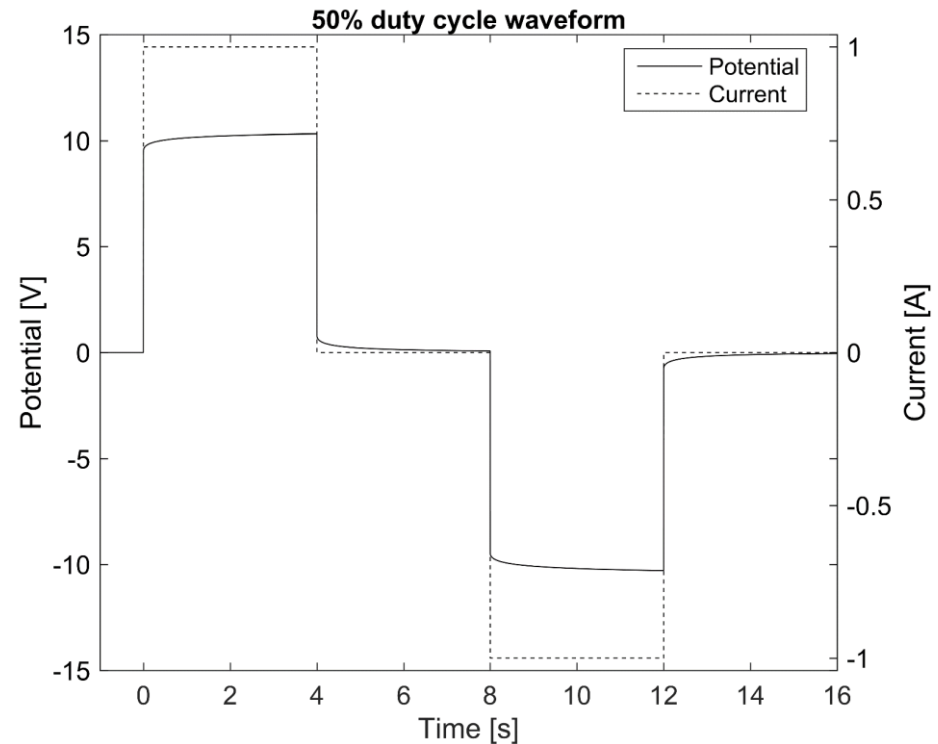
PER-IVAR OLSSON, GIANLUCA FIANDACA, JAKOB JUUL LARSEN,  
TORLEIF DAHLIN, ESBEN AUKEN



# Outline

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- Background
- Signal processing:
  - IP gating.
  - Drift removal.
  - Spikes.
  - Harmonic noise.
  - Tapered gating.
- IP gate data uncertainty.
- Conclusions.



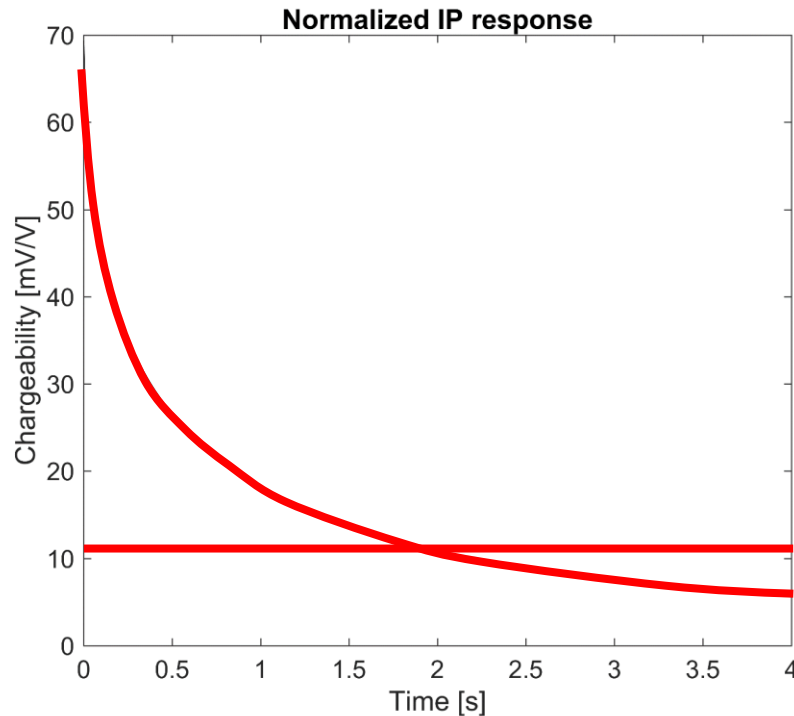
# Background

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- Increase spectral information content by extending the available time range.
- Increase TDIP data reliability and quality.
- Data driven uncertainty estimates for induced polarization.



# Background



Spectral chargeability

e.g. Cole-Cole model

$$m_{int} = \frac{1}{V_{DC} \Delta t} \int_0^{\infty} V(t) dt$$

$$V_{IP}(t) = m_0 \sum_{j=0}^{\infty} (-1)^j \left( \frac{t}{\tau} \right)^{jc} \Gamma(1 + jc)^{-1}$$

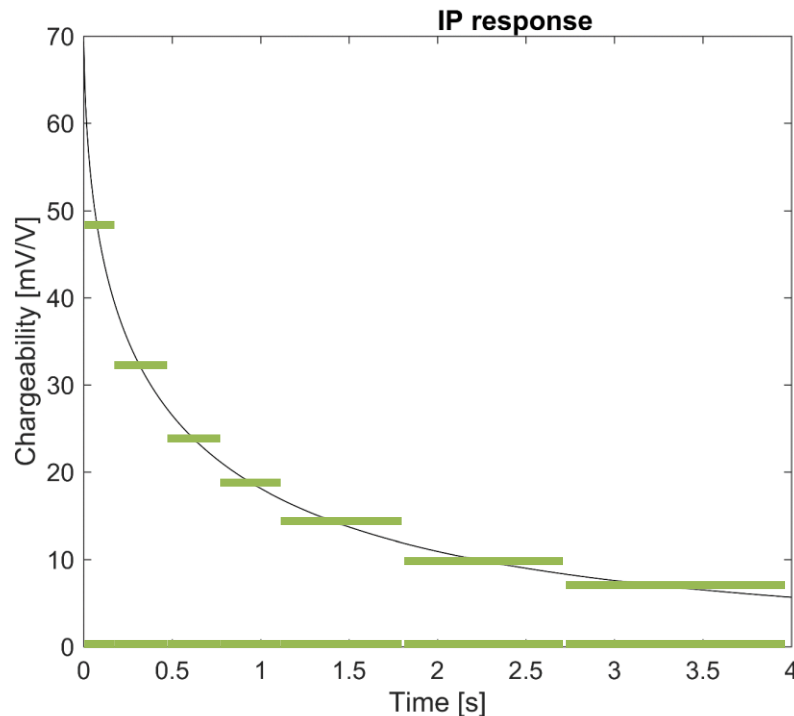
Euler's Gamma function:

$$\Gamma(x) = \int_0^{\infty} y^{x-1} e^{-y} dy$$



# IP Gating

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IP response is down-sampled in windows or “gates”.

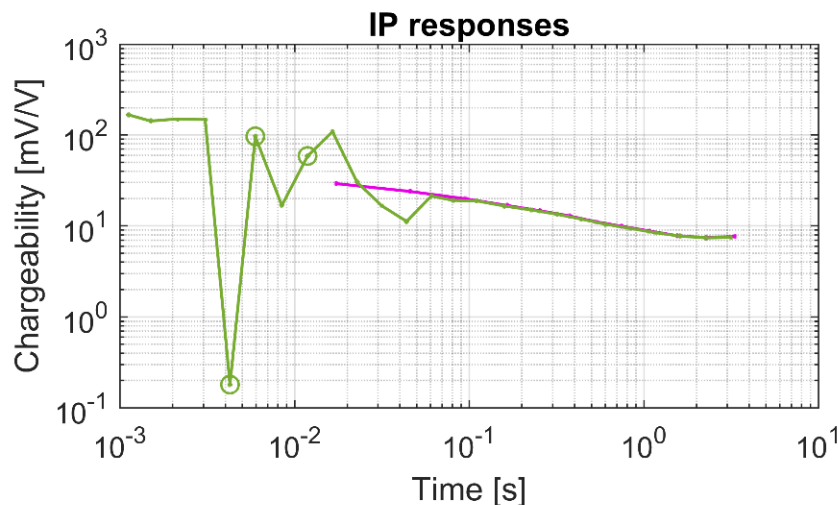
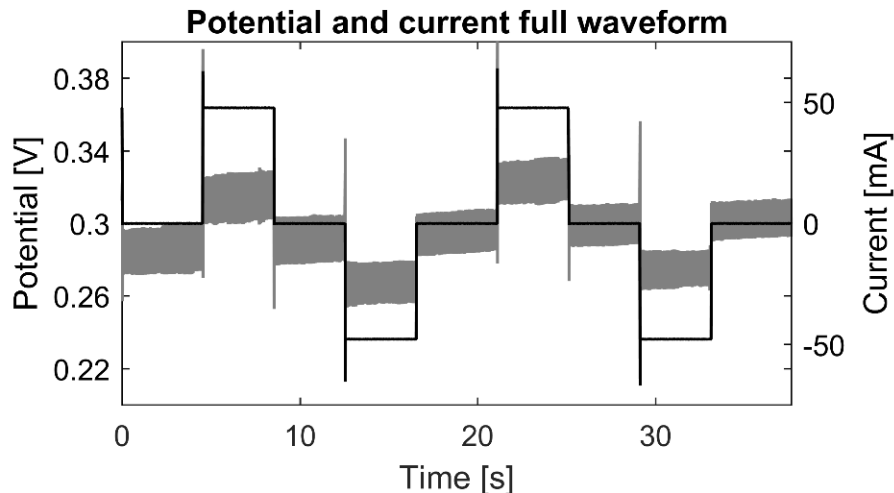
Logarithmically increasing window width to compensate for lower signal-to-noise ratio.

Gates are multiples of 20 ms to suppress harmonic noise.

BUT: We lose early time information if using long gates!



# Processing today



Linear background drift  
removal and log-gating:

Increase of chargeability at  
late times due to poor  
performance of linear  
background model.

Erratic behaviour at early  
times while gates are  $< 20\text{ms}$   
due to harmonic noise.



# Processing challenges

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- Background drift.
- Spikes.
- Harmonic noise.
- EM coupling.

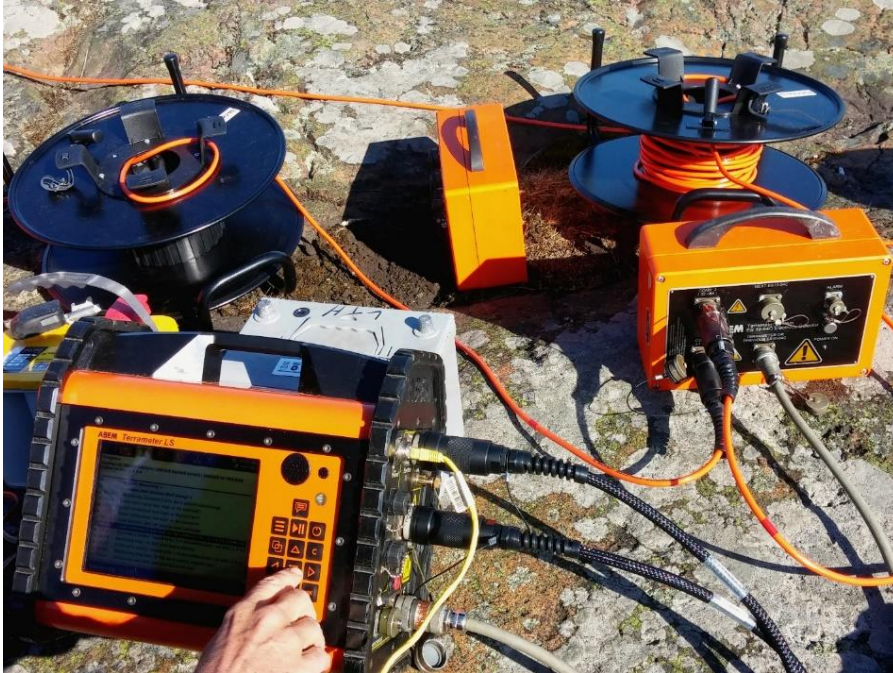
$$u_{measured} = u_{response} + u_{drift} + u_{spikes} + u_{harmonic\ noise} + u_{other}$$





# Background drift

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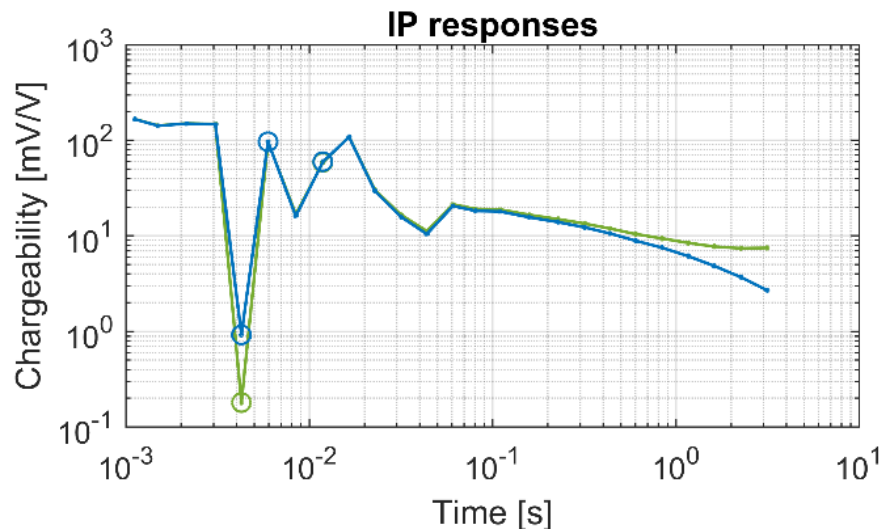
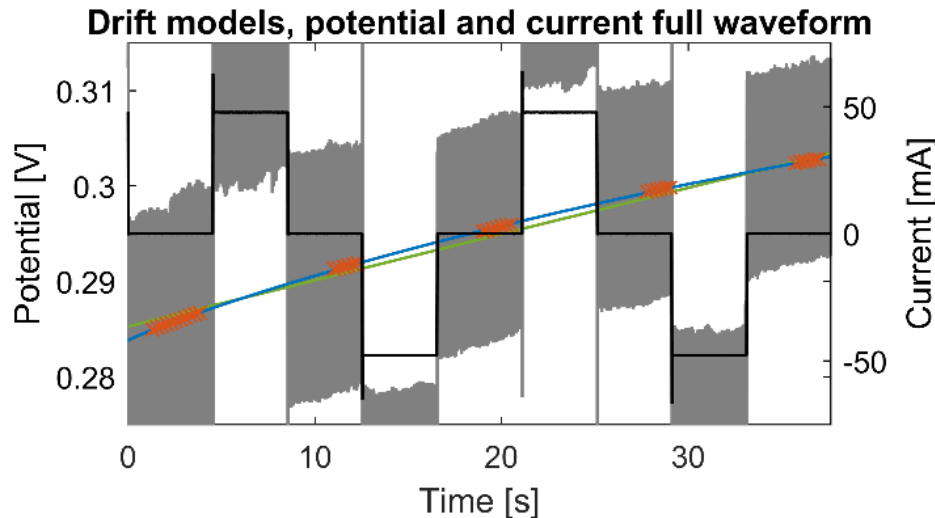


Main contributor:  
current induced electrode  
polarization from previous  
current injections.





# Background drift



Drift is estimated from averaged (20 ms) points. To reduce IP response influence, only a subset of points from end of off-time is used.

Cole-Cole drift model suitable for describing depolarization.



# Spikes

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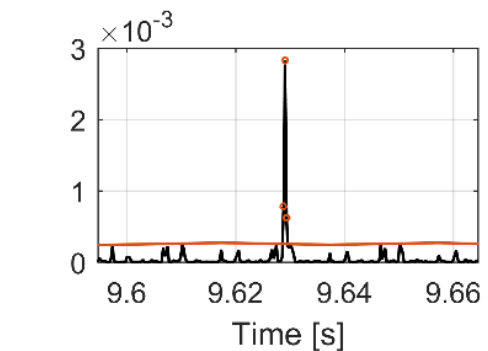
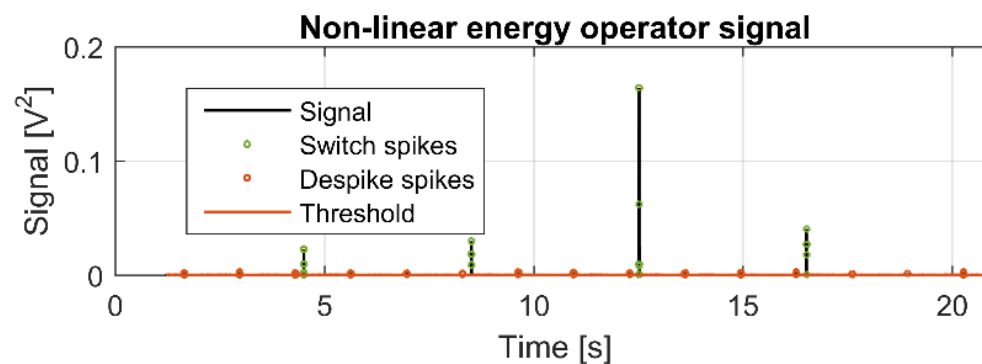
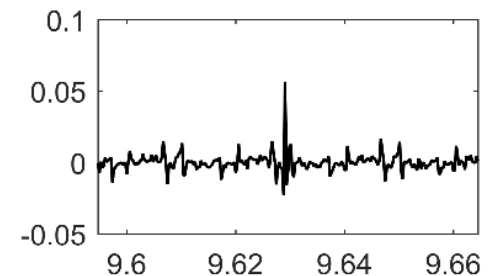
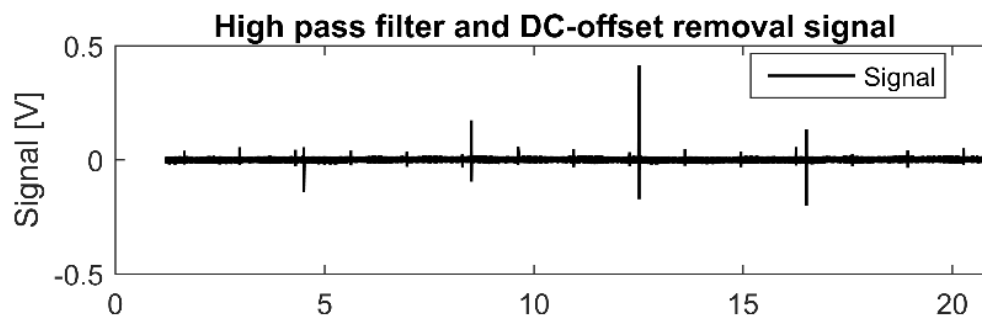
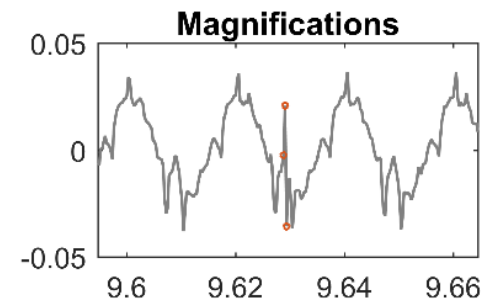
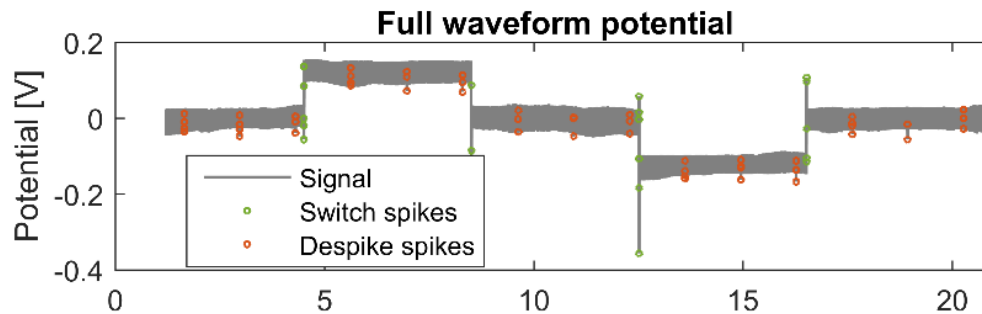
Electrical fences for livestock management.

EM coupling from current pulse transients.



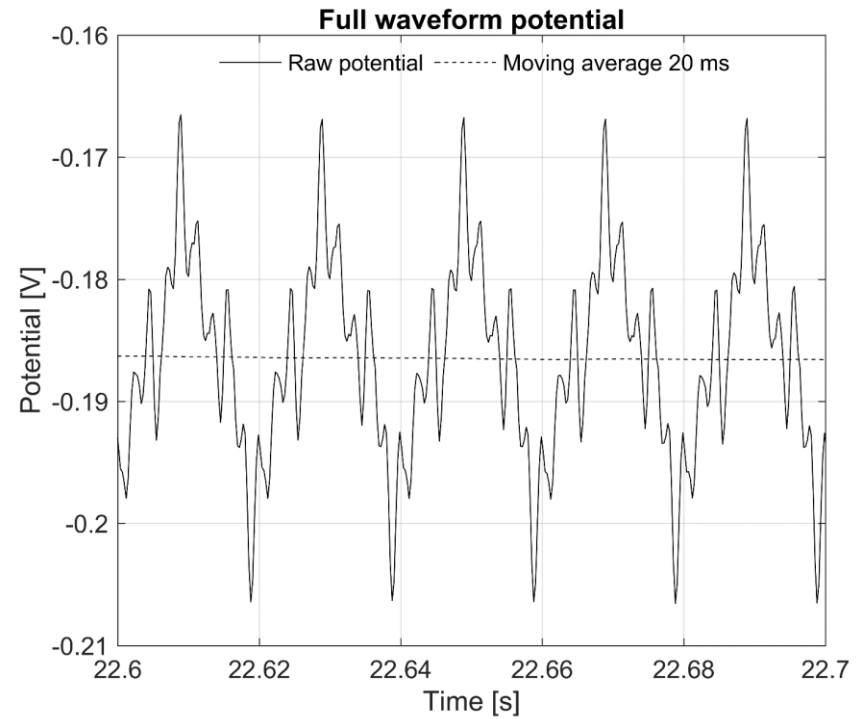
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# Spikes



# Harmonic noise

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# Harmonic noise

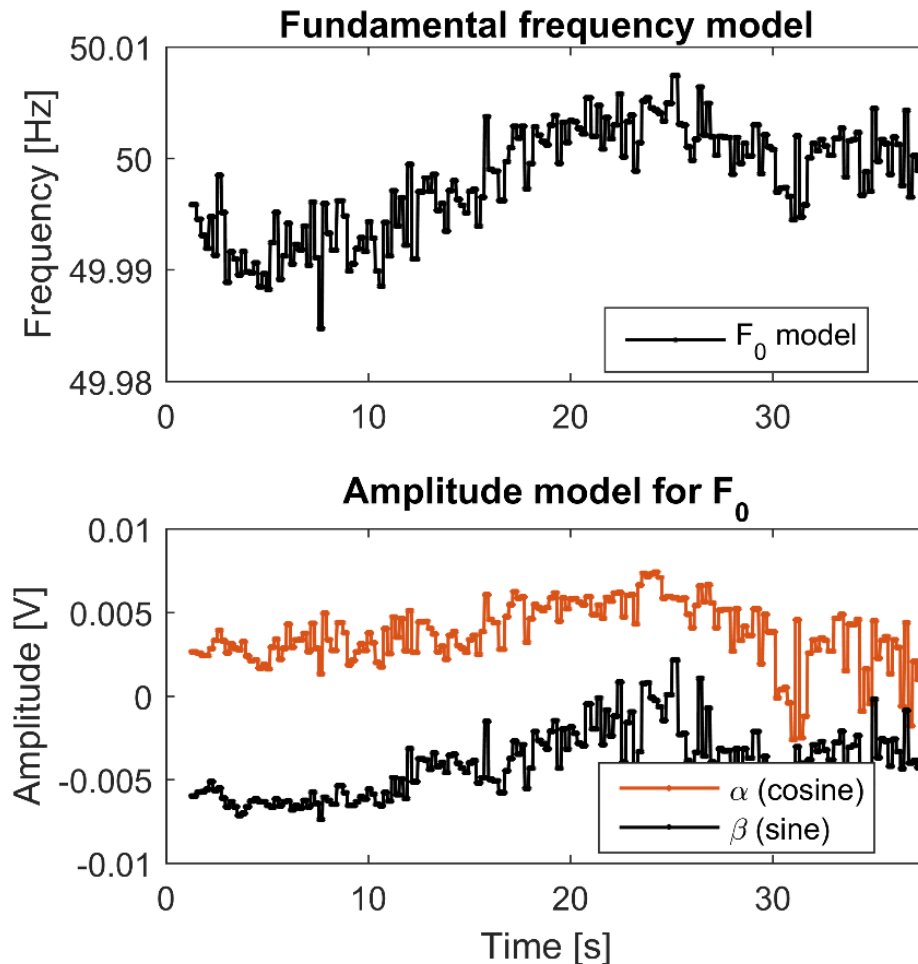
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$$u_{\text{harmonic noise}}(n) = \sum_m \left( \alpha_m \cos \left( 2\pi m \frac{f_0}{f_s} n \right) + \beta_m \sin \left( 2\pi m \frac{f_0}{f_s} n \right) \right)$$
$$E_{\text{residual}} = \sum_n \left( u_{\text{measured}}(n) - u_{\text{harmonic noise}}(n) \right)^2$$

Minimizing  $E_{\text{residual}}$  to find parameters  $\alpha_m$ ,  $\beta_m$  and  $f_0$ .



# Harmonic noise

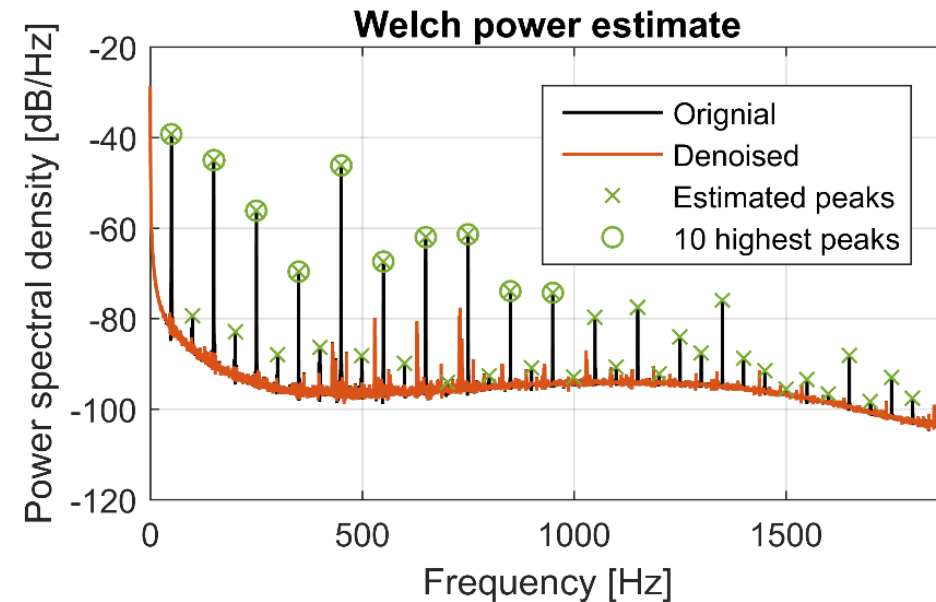


Signal is segmented so that  $\alpha_m$ ,  $\beta_m$  and  $f_0$  variation is small.

Segment length is a trade-off between parameter accuracy and variation.



# Harmonic noise



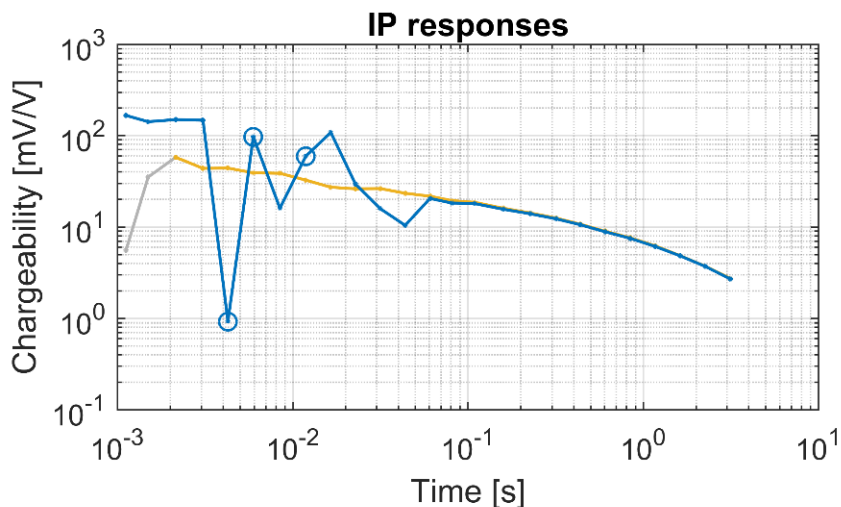
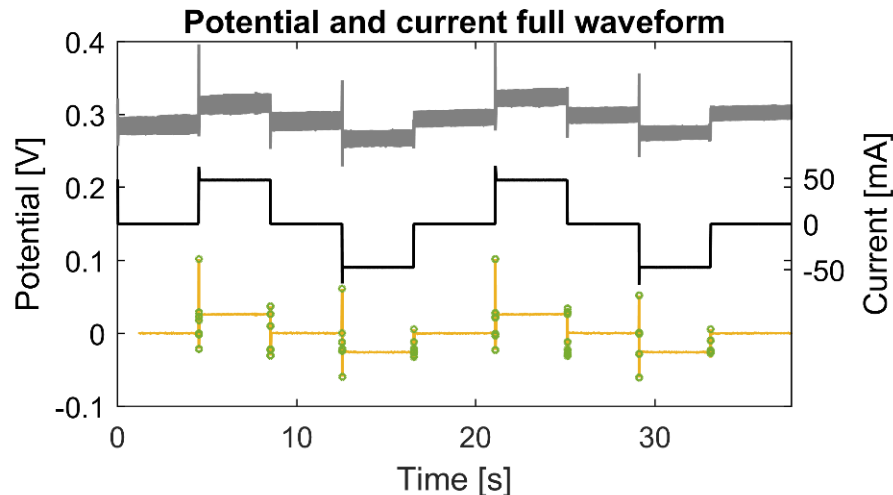
$f_0$  and harmonics energy is reduced to “baseline energy”.

A subset of highest harmonics is used for finding  $f_0$ .





# Harmonic noise

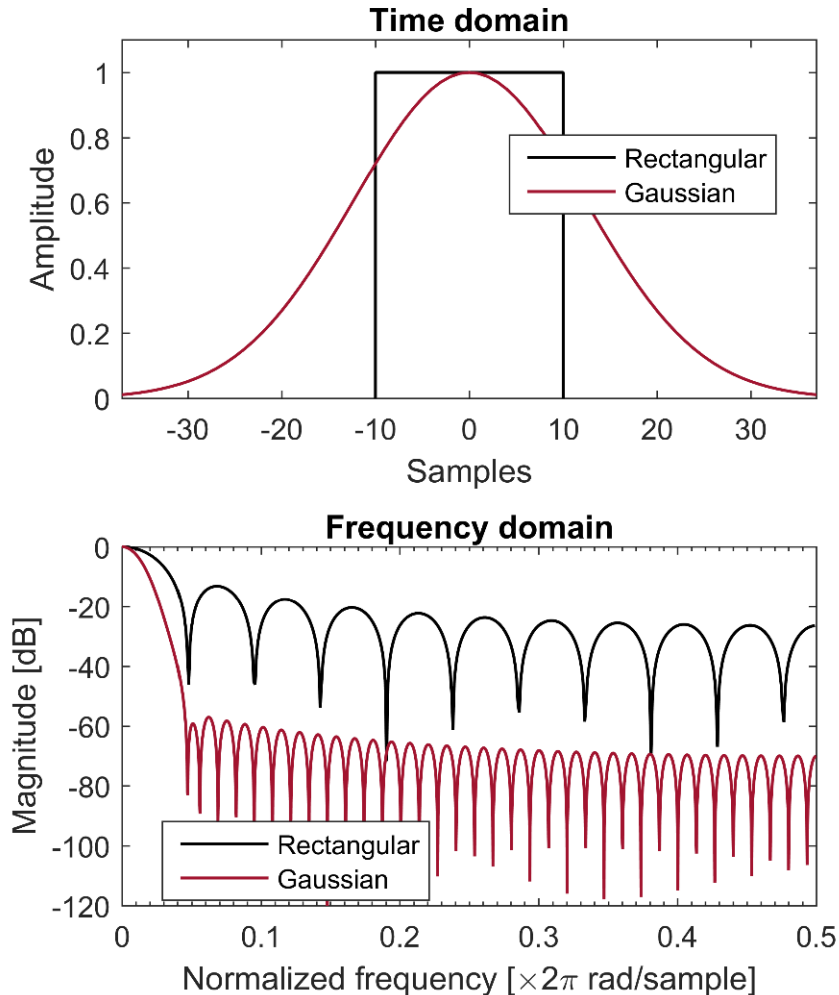


Erratic behaviour at early times is removed.

Gates containing spikes at current pulse switches can be rejected.



# Tapered gating

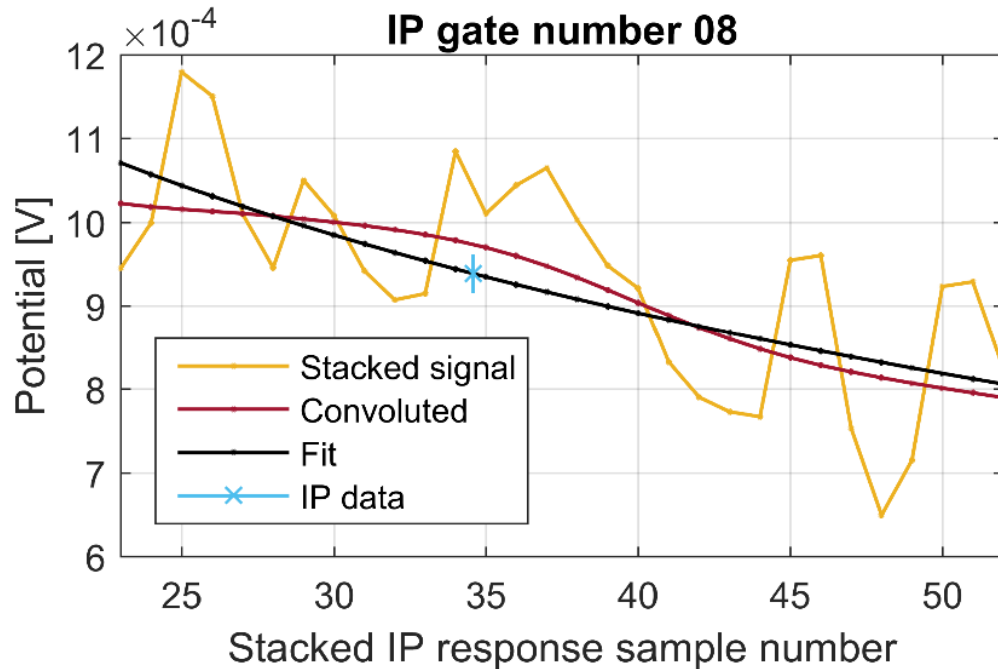


Gaussian windows 3.5 times wider than rectangular gate.

Same width of main lobe but 40 dB higher noise suppression!



# Tapered gating



Convolution of stacked signal.

Linear fit of convoluted signal in lin-log space.

Evaluates gate value at linear fit.

Estimate uncertainty from convoluted signal and linear fit.



# Uncertainty estimate

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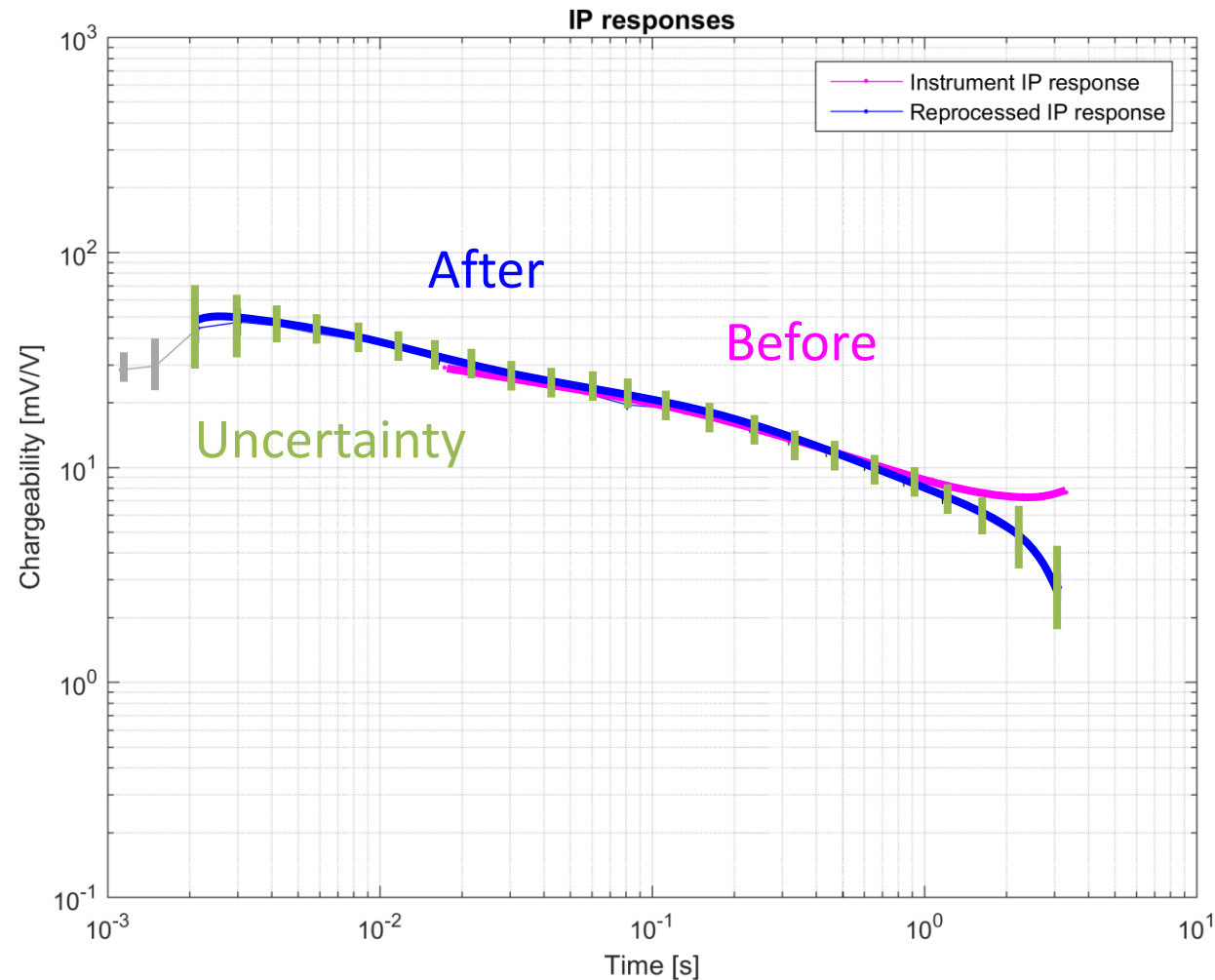
$$STD_{total} = \sqrt{STD_{gating}^2 + STD_{drift}^2 + STD_{uniform}^2}$$

$$STD_{drift} = \sqrt{\frac{1}{N_{drift\ data}} \sum_{k=1}^{N_{drift\ data}} (drift\ data(k) - drift\ fit(k))^2}$$

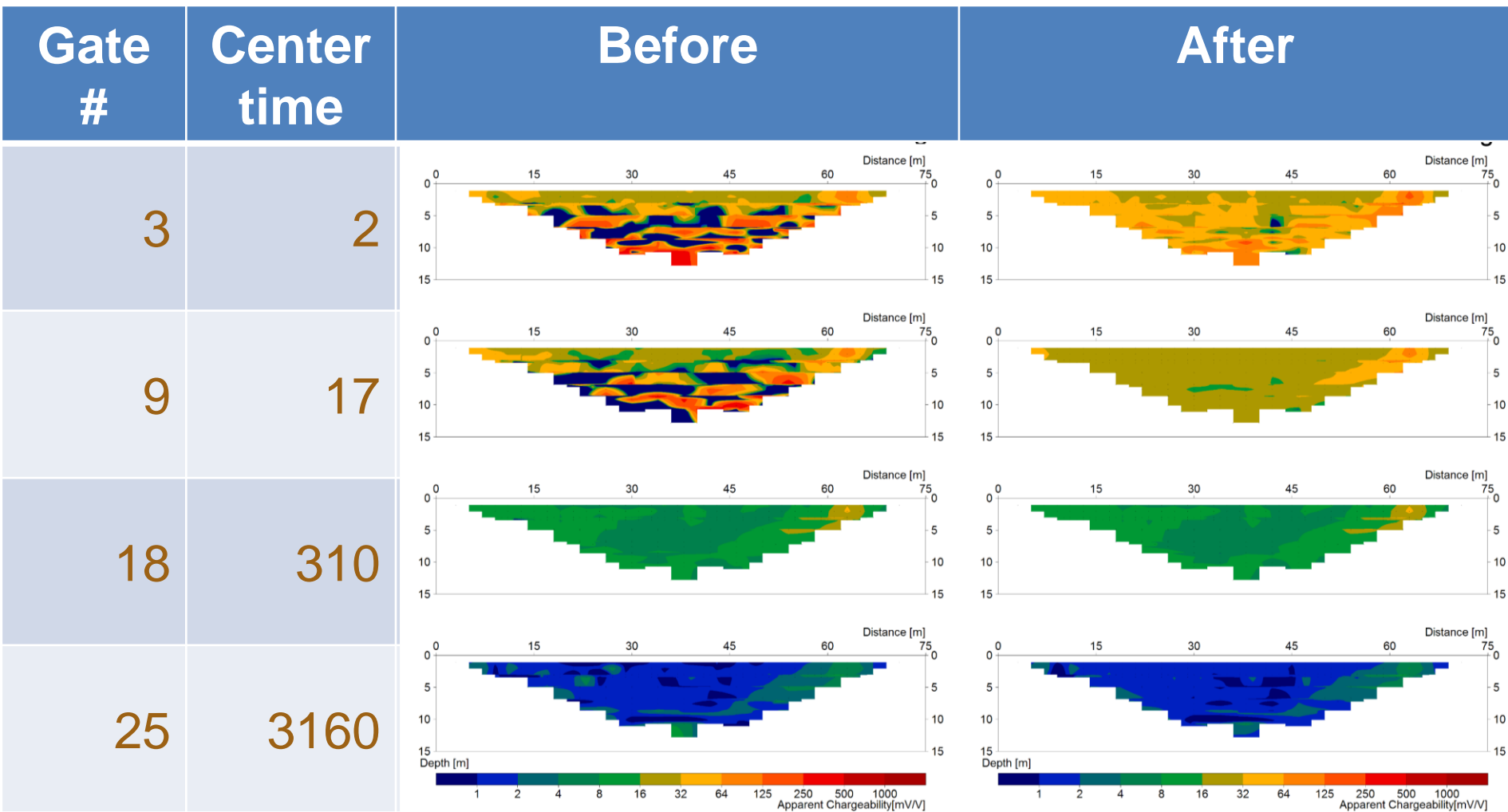
$$STD_{gating} = \sqrt{\frac{1}{N_{gate\ samples}} \sum_{n=1}^{N_{gate\ samples}} (convoluted\ data(n) - linear\ fit(n))^2}$$



# Spectral information content



# Spectral information content



# Conclusions

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- Spectral information from time domain IP surveys is doubled compared to existing procedure.
- TDIP data reliability and quality is increased.
- Data driven uncertainty estimates for individual TDIP gates.





# Thank you for listening!

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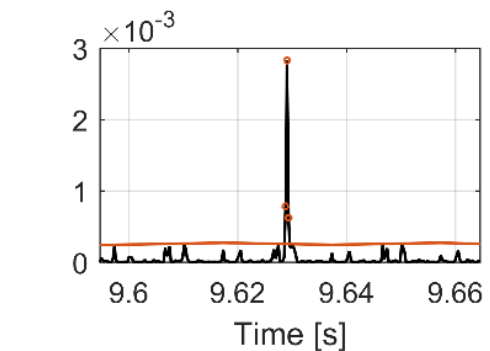
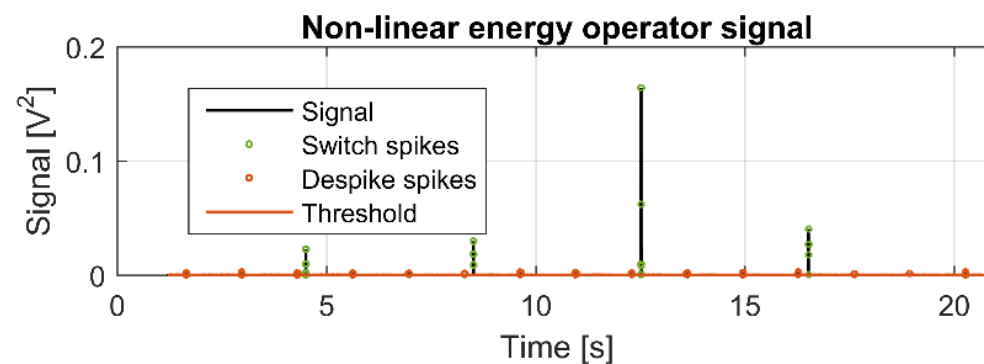
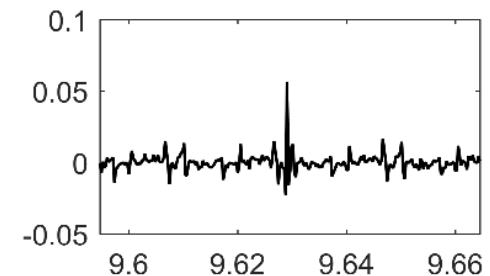
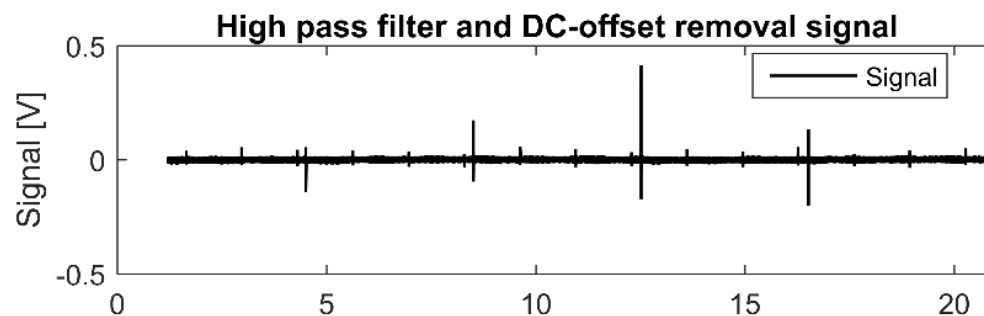
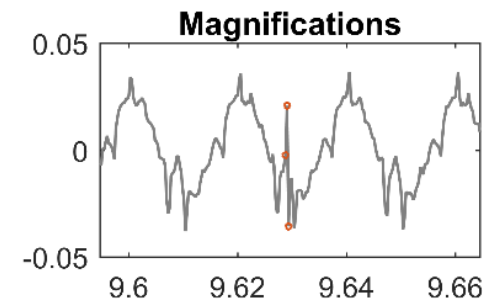
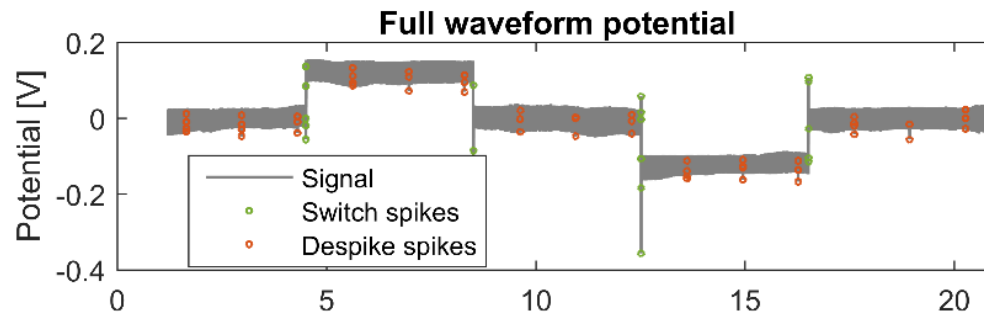
# Spikes

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$$u_2(n) = u_{\text{measured}}(n) - u_{\text{measured}}(n - 1)$$
$$u_3(n) = \text{abs}(u_2(n)^2 - u_2(n - 1)u_2(n + 1))$$



# Spikes



# Tapered gating

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$$u_{IP,stacked}(k) = \frac{1}{N_{pulses}} \sum_{j=1}^{N_{pulses}} (-1)^{j+1} u_{processed}(k + S_{IP}(j) - 1)$$

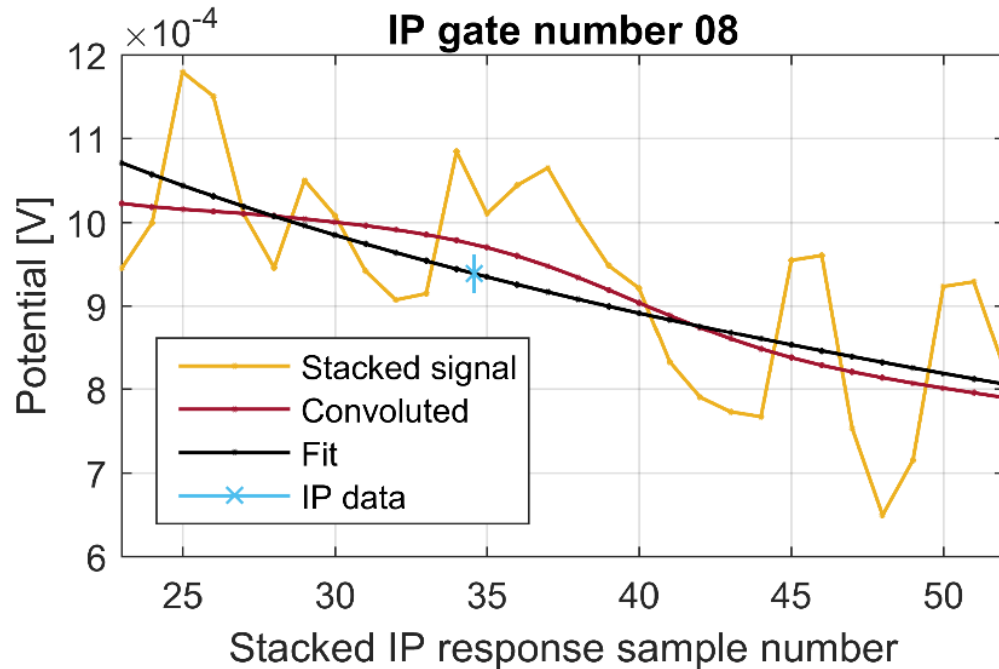
$$u_{IP,gated}(m) = \frac{1}{N_{samples}(m)} \sum_{i=1}^{N_{samples}(m)} u_{IP,stacked}(i + S_{gate}(m) - 1)$$

$$w_m(i) = e^{-\frac{1}{2} \left( \alpha \frac{i}{(N_{window}(m)-1)/2} \right)^2}; \quad |i| \leq (N_{window}(m) - 1)/2$$

$$\begin{aligned} & u_{IP,conv}(m)(j) \\ &= \frac{1}{\sum w_m} \sum_{i=-\frac{N_{window}(m)-1}{2}}^{\frac{N_{window}(m)-1}{2}} u_{IP,stacked}(j + S_{gate}(m) - 1 - i) w_m(i) \end{aligned}$$



# Tapered gating



Gaussian windows 3.5 times wider than gate.

40 dB noise suppression for higher frequencies!

